## Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application:

## **Listing of Claims:**

## Claims 1-24 (canceled)

1	Claim 25 (new): A process for measuring
2	three-dimensional objects in a three-dimensional
3	environment, comprising the steps of:
4	taking at least one image of said environment by at
5	least one camera;
6	detecting discontinuities of appearance in the image;
7	relating said discontinuities with geometric contours,
8	said contours having positions and shapes in the image
9	which are defined by parameters including numerals;
10	matching said geometric contours with said
11	discontinuities by adjusting said parameters;
12	relating said geometric contours with geometric
13	objects in the three-dimensional environment, positions and
14	shapes of said geometric objects in the environment being
15	defined by parameters including numerals;
16	estimating said positions and shapes of said geometric
17	objects in the three-dimensional environment in computing
18	geometric projections of said geometric objects onto said
19	at least one image according to a match between said

- 20 projection and said geometric contours; and,
- creating a representation of the three-dimensional
- 22 environment, said representation comprising said geometric
- objects, according to the parameters defining the positions
- 24 and shapes of said geometric objects.
  - Claim 26 (new): The process according to claim 25,
  - 2 characterized in that the geometric contours include dots,
- 3 straight lines, ellipses, and the objects include circles,
- 4 cylinders, straight lines and dots.
- Claim 27 (new): The process according to claim 26,
- 2 characterized in that the parameters include plane
- 3 Cartesian coordinates, angles and lengths.
- Claim 28 (new): The process according to claim 25,
- 2 characterized in that said at least one image in converted
- into an image of a potential function computed on pixels of
- 4 said at least one image, the potential function giving
- 5 extreme values at said discontinuities.
- 1 Claim 29 (new): The process according to claim 28,
- characterized in that the potential function includes a
- 3 term taking account of areas with very low intensity of
- 4 gray on the images.

- Claim 30 (new): The process, according to claim 25,
- wherein said representation comprises a position of said at
- 3 least one camera.

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Claim 31 (new): The process according to claim 30,
wherein said geometric projections are determined from the
position of said camera and positions of said geometric

objects in the representation.

- Claim 32 (new): The process according to claim 25,
  wherein the representation initially comprises information
  on at least the positions and shapes of said geometric
  objects which is inputted manually or from a computer
  description file, and the representation is created in
  progressively amending said information so that the match
  between the projection of said geometric objects and said
  - Claim 33 (new): The process according to claim 25, wherein a plurality of said images is taken, and said representation of the three dimensional environment is amended in repeating the process for each of said images.

geometric contours of said at least one image is improved.

Claim 34 (new): The process according to claim 33,
wherein said representation of the three-dimensional
environment in amended in amending the positions and shapes

- of said geometric objects for each of said images.
- 1 Claim 35 (new): The process according to claim 33,
- wherein said representation of the three-dimensional
- 3 environment is amended in including said geometric objects
- 4 into said representation in repeating the process for
- 5 different ones of said images.